



# DL-MES5 DATASHEET

LARGE-RANGE OPTICAL TURBIDITY AND TEMPERATURE SENSOR FOR LORAWAN®



### **FEATURES**

LoRaWAN®-enabled large-range optical infrared turbidity and temperature sensor.

Suspended solid: 0 ... 50 g/L.

Sludge blanket: 0 ... 100 %.

Turbidity: 0 ... 4000 FAU.

Cable length: 7 m (custom lengths on request).

Compatible with LoRaWAN® networks of any

provider.

Place and measure: no setup required.

Configurable via command line interface and downlink command interface.

Unattended real-time monitoring for several years without replacing batteries.

Robust polycarbonate enclosure: weatherproof, impact-, UV-resistant (IP67).

Standard alkaline (C-type) batteries.

CE compliant, Radio Equipment Directive (RED) 2014/53/EU.

## **APPLICATIONS**

Outdoor remote monitoring.

Urban wastewater treatment.

Industrial effluent treatment.

Sludge treatment.

Dredging site.



# **DESCRIPTION**

Sensor data are transmitted in real-time using LoRaWAN® radio technology. LoRaWAN® enables encrypted radio transmissions over long distances while consuming very little power. The user can obtain sensor data through Decentlab's data storage and visualization system, or through the user's own infrastructure. Visit <a href="www.decentlab.com">www.decentlab.com</a> for more information about Decentlab's data cloud service.

# **DEVICE VARIANTS**

Name	Variant
DL-MES5-001	001

# **DEVICE SPECIFICATIONS**

### DEVICE LOGGING FUNCTION

Sampling interval	10 min (configurable through the user interfaces)
Data upload interval	10 min (configurable through the user interfaces)
Reported sensor data (average of samples)	Sensor status Temperature Sludge blanket Suspended solid Turbidity in FAU Battery voltage

### TURBIDITY

Operating principle	Optical IR signal (870 nm), 5 mm path, temperature regulation
Measurement range	0 50 g/L (suspended solid) 0 100 % (sludge blanket) 0 4000 FAU (turbidity)
Resolution	0.01 g/L (suspended solid) 0.01 % (sludge blanket) 0.01 FAU (turbidity)
Accuracy	< 10 % (suspended solid) ±2 % (sludge blanket) ±5 % (turbidity) @ 200 4000 FAU

### **TEMPERATURE**

Operating principle	Thermistor	
Measurement range	0 50 °C	
Resolution	0.01 °C	
Accuracy	0.5 °C	



### RADIO / WIRELESS

Wireless technology LoRaWAN®

Wireless security AES-128 data encryption LoRaWAN® device type Class A end-device

Supported LoRaWAN® features OTAA, ABP, ADR, adaptive channel setup

Wireless range > 10 km (line of sight¹), approx. 2 km (suburban)

RF transmit power 14 dBm (25 mW)
Effective radiated power 11.9 dBm maximum<sup>2</sup>

Receiver sensitivity -146 dBm<sup>3</sup>

Frequency bands 868 MHz (EU version), 915 MHz (US, AS, AU versions)<sup>4</sup>

Antenna Integrated omnidirectional antenna featuring a near-perfect

radiation pattern<sup>2</sup>

### POWER SUPPLY

Internal battery type	2 × alkaline C batteries (LR14)
Power consumption (average)	≤ 0.5 mW (10 min interval)
Battery lifetime estimation⁵	9.1 years (10 min interval, SF7) 3.8 years (10 min interval, SF12) 15.7 years (60 min interval, SF7) 11.2 years (60 min interval, SF12)

#### **OPERATING CONDITIONS**

Sensor head	0 50 °C Non-freezing
Sensor device	-20 50 °C 0 100 % RH

### MECHANICAL SPECIFICATIONS

Dimensions	135 × 81 × 70 mm (not including sensor / cable)
Sensor head	Length: 281 mm, diameter: 64 mm
Weight	1400 g including batteries and sensor (1270 g without batteries)
Enclosure rating	Polycarbonate; weatherproof, impact-, UV-resistant (IP66/IP67). Pressure equalizer plug with PTFE membrane (IP68).
Cable length	7 m

- 1 Decentlab reports successful transmissions over 56 km distance and more
- 2 See Appendix A: Antenna performance
- 3 Specified by radio chip vendor
- 4 Contact us for region specific options
- 5 Including alkaline battery self-discharge of 3.6 % per year (conservative estimation); battery capacity: 20000 mWh.



### OPERATING INSTRUCTIONS

The product usually requires no user interaction. If you open the enclosure, e.g. in order to replace the batteries, unscrew the four plastic screws and carefully open the lid.

CAUTION: Make sure the sensor unit does not drop out of the enclosure while opening! Do not touch the electronic components and sensors!

NOTE: When closing the lid, make sure the lid is fitted the right way, so that the enclosure is properly sealed: A little nose in the enclosure fits a notch in the lid and vice versa.

### REPLACING BATTERIES

Insert 2 high-quality alkaline C batteries (LR14) into the battery holder on the back side of the sensor unit. The device operates until the battery voltage drops to 2.0 V. Always replace both battery cells with two identical fresh batteries.

### **USER BUTTON AND LEDS**

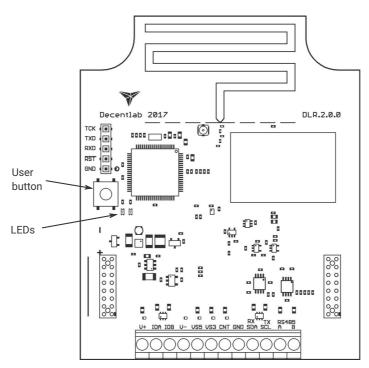


Illustration 1: Sensor unit showing the user button and LEDs. The battery holder is on the back side of the sensor unit.



### **OPERATING MODES**

The device has four operating modes:

- Reset: System (re-)start; both LEDs fade in and out.
- Active mode (ON): Periodic measurements and data transmissions; green LED flashes for each measurement.
- Sleep mode (OFF): No measurements and data transmissions (power save mode, for shelf storage). LEDs are off.
- Test mode: Measurements and data transmissions at fastest possible rates; blue LED is on.
  NOTE: Use only momentarily, e.g. for testing the sensor or the wireless connection. The device
  will switch automatically to active mode after 20 minutes.

#### SWITCHING BETWEEN OPERATING MODES

The user button allows to switch between the operating modes as shown in Illustration 2 and Illustration 3. To perform a device reset, switch to sleep mode first (if necessary) by pushing and holding the button for 3 seconds until the LEDs flash three times; wait 3 seconds; then push and hold the button for 3 seconds until the LEDs fade in and out. To switch between active and test mode, push the button for 1 second (blue LED on / off). If the blue LED is off, the device is in active or sleep mode. If the blue LED is on, the device is in test mode.

HINT: To check whether the device is active or in sleep mode (on or off), push the button twice; if the blue LED goes on and off, the device is in active mode; otherwise, the device is in sleep mode.

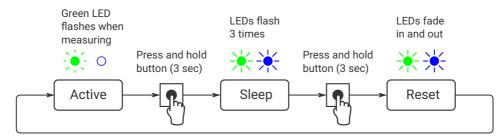


Illustration 2: Switching between active and sleep mode (switch off / on, reset).

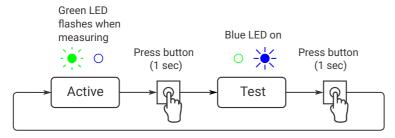


Illustration 3: Switching between active and test mode.



### MEASUREMENT CYCLE (ACTIVE MODE)

During the active mode, the device periodically reads the sensors with sampling period  $T_S$  = 10 minutes (default, configurable). When the send period  $T_{TX}$  =  $n \cdot T_S$  (default: n = 1, configurable) has expired, the device computes the average of the collected sensor values (at most 20 values). After a random delay of 0 ... 8 seconds, the device transmits the aggregated sensor data. If the device has not yet joined the LoRaWAN® network, it will try to join until it succeeds (maximum 3 attempts per sampling period). Afterwards, it will transmit the data (TX data). Following the data transmission, two receive slots are opened (RX1 and RX2). During these time slots, the device is ready to receive data from the network (downlink messages) as defined in the LoRaWAN® specification.

As shown in the diagrams, the device is idle most of the time. During the idle time, the current consumption is extremely low.

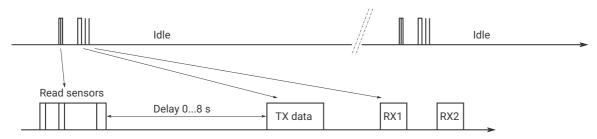


Illustration 4: Device activity during the active mode.

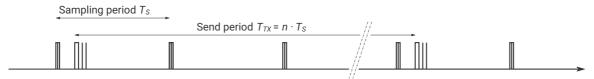


Illustration 5: Sampling period vs. send period. Default:  $T_S = 10$  min,  $T_{TX} = 1 \cdot 10$  min = 10 min.

#### LED SIGNALING (ACTIVE MODE)

- · Read sensors: green LED flashes once.
- Data sent successfully: green LED flashes 2 times.
- · Data could not be sent: green LED flashes 4 times.



### **DEVICE CONFIGURATION**

The user can configure a rich set of device parameters, such as sampling interval, LoRaWAN® data rate, ADR settings and many more. If desired, the parameter settings can be stored permanently in the internal non-volatile memory. The user can configure the device via two interfaces:

- Command line interface: via a serial cable (UART USB) connected to a computer.
- Downlink command interface: over the air using LoRaWAN® downlink messages.

For a full description of the command line interface and the downlink command interface, please find the specific documents on <a href="https://www.decentlab.com/support">www.decentlab.com/support</a>.



# MOUNTING INSTRUCTIONS

Prefer a mounting location which is protected against rain and direct sun radiation.

For best radio performance, install the device upright with the cable towards ground; ideally, in such a way that the device lid faces roughly in the direction of the next gateway. Also, the higher above ground, the better. Avoid metallic objects close to the device.

The housing includes 4 threaded bushes (M4) in a  $90 \times 60$  mm rectangle (see Illustration 6). This enables easy installation using standard M4 bolts.

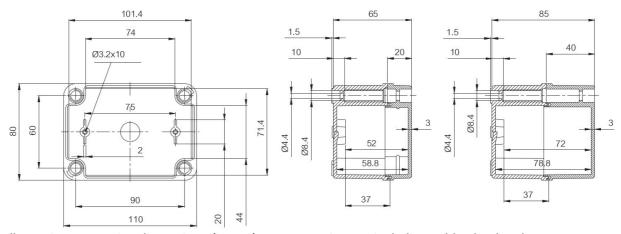


Illustration 6: Housing dimensions (in mm). Note: Drawing not including cable gland and sensor.



# ORDERING INFORMATION

REFERENCE	VERSION	REGION (LORAWAN®)
DL-MES5-001-EU868	001	Europe
DL-MES5-001-US915	001	North America
DL-MES5-001-AS923	001	Asia
DL-MES5-001-AU915	001	Australia, South America
Other options: contact us	S	



# SENSOR DATA MESSAGE FORMAT

### Message:

- Message length is variable, depending on which sensor data are included. Minimum length is 5 bytes (header only). Maximum length is 5 bytes + all sensor data (see below).
- Integers are big endian: MSB first byte, LSB last byte.

#### Header:

Version Device ID Flags	;
-------------------------	---

- Version: 1 byte; version = 2 for current protocol version.
- Device ID: 2 bytes; 0...65535.
- Flags: 16 bits: flag 15 | flag 14 | ... | flag 0 (LSB).
- The flags indicate, if data of the respective sensors are included in the message or not:
   Flag n == 1: sensor n data included; flag n == 0: not included.

### **DECODER SOFTWARE**

For message decoder software, please go to <a href="https://www.decentlab.com/support">https://www.decentlab.com/support</a>, where you find code examples in JavaScript and other programming languages.

### **DETAILS**

FIELD	PARAMETER NAME	TYPE	CONVERSION	UNIT
Header	Version	uint8		
Header	Device ID	uint16		
Header	Flags	uint16		
Sensor 0	Status	uint16	Χ	
Sensor 0	Temperature	uint16	(x - 32768) / 100	°C
Sensor 0	Sludge blanket	uint16	x / 100	%
Sensor 0	Suspended solid	uint16	x / 100	g/L
Sensor 0	Turbidity	uint16	x / 10	FAU
Sensor 1	Battery voltage	uint16	x / 1000	V

### Status value interpretation:

- Status = 0: measurement okay
- Status > 0: measurement may be out of range



# EXAMPLE 1 (ALL SENSOR DATA INCLUDED)

Message (hex):

#### 024E030003000088E6210800F223650AF5

 02
 Version
 =
 2

 4E03
 Device ID
 =
 19971

 0003
 Flags
 =
 0b000000000000000011

 0000
 Status
 =
 0

 88E6
 Temperature
 =
 22.78
 deg

 2108
 Sludge blanket
 =
 84.56
 %

 00F2
 Suspended solid
 =
 2.42
 g/L

 2365
 Turbidity
 =
 906.1
 FAU

 0AF5
 Battery voltage
 =
 2.805
 V

# EXAMPLE 2 (ONLY BATTERY VOLTAGE)

Message (hex):

02

### 024E0300020AF5

Version

4E03	Device ID	=	19971	
0002	Flags	=	0b0000000000000010	
	Status	=		
	Temperature	=		deg
	Sludge blanket	=		%
	Suspended solid	=		g/L
	Turbidity	=		FAU
0AF5	Battery voltage	=	2.805	V

= 2



# **DECLARATION OF CONFORMITY**

We,

Decentlab GmbH Kriesbachstrasse 30 8600 Dübendorf Switzerland



declare under our own responsibility that the product

Reference	Name
DL-MES5-xxx-EU868	Large-Range Optical Turbidity and Temperature Sensor for LoRaWAN®

to which this declaration refers conforms with the relevant standards or other standards documents

- EN 300 220-1 V3.1.1: 2017-02
- EN 300 220-2 V3.1.1: 2017-02
- EN 301 489-1 V2.2.0: 2017-03
- EN 301 489-3 V2.1.1: 2017-03

### According to

- · Radio Equipment Directive (RED) 2014/53/EU
- Electromagnetic Compatibility (EMC) Directive 2014/30/EU

Dübendorf, 20. February 2025

Reinhard Bischoff, Managing Director

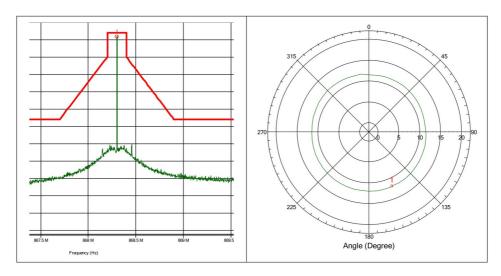
1. Nischoff

# APPENDIX A: ANTENNA PERFORMANCE

No : **DE.17.039.F01** Page 21 / 24

#### **Measurement Results:**

EUT	DLR1-LP8		
Test performed	Effective radiated power (ERP)		
Verdict, Test	Pass		
Modification	None		
Mode of operation	Transmitter mode		
Test date, time	13.06.2018 09:37:06		
Antenna height	1.30 m Antenna polarization Vertice		Vertical
EUT position	0 to 360 Degree Antenna distance 3 m		3 m
Measurement settings	Radimation Version: 2017.1.6, RBW: 1 kHz, VBW: 300 kHz, Sweep time: Auto [120 ms], Step freq: Linear: 250 Hz steps, Attenuator: Auto [10 dB], Internal preamp: 20 dB, Measure time: 10 ms, Measurement equipment: TP_RE_30M-1G_ETSI_Ver		



### **Detected peaks**

Peak Number	Frequency	Peak	Peak Difference	Status	Angle	Height	Polarization
1	868.302 MHz	11.9 dBm	-2.14 dB	Pass	157 Degree	1.3 m	Vertical

#### Limits:

ETSI EN 300 220-2, Table C.1	25 mW e.r.p
OFB: 863 MHz to 870 MHz	
<= 0.1% duty cycle or polite spectrum access	(14 dBm)

EMV Prüfstelle Zürich – Technopark – 8005 Zurich

# **DISCLAIMER**

Specifications and information in this document are subject to change without notice.

Decentlab products are not warranted or authorized for use as critical components in medical, lifesaving, or life-sustaining applications, or other applications where a failure would reasonably be expected to cause severe personal injury or death.

# **CONTACT INFORMATION**

 $\underline{www.decentlab.com/contact}$ 

mail@decentlab.com

+41 44 809 35 90

Decentlab GmbH Kriesbachstrasse 30 8600 Dübendorf Switzerland

WELKO Av. Providencia 2330, Of. 63 +56 9 3174 3870 / +56 9 3427 0017 ventas@welko.cl - www.welko.cl

